

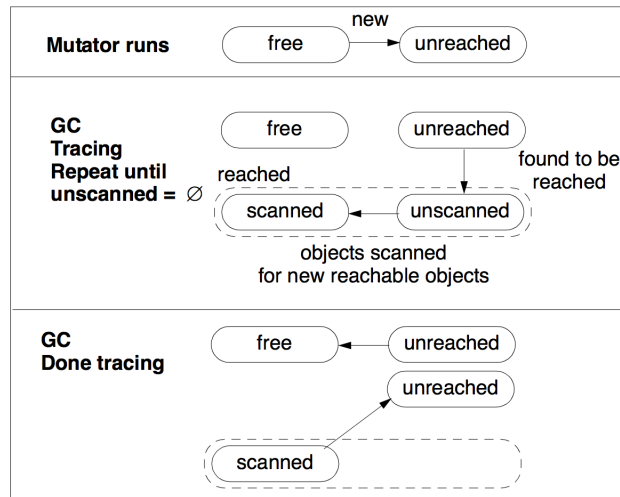
# Lecture 18

## Advanced Garbage Collection

- I. Break Up GC in Time (Incremental)
- II. Break Up GC in Space (Partial)

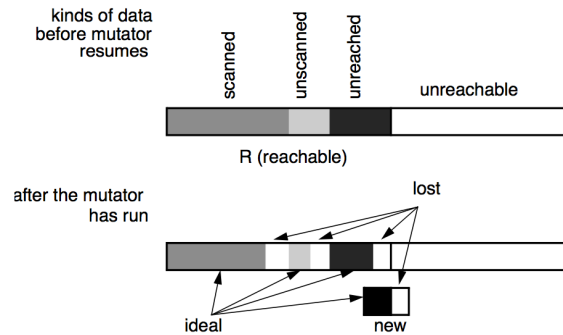
Readings: Ch. 7.6.4 - 7.7.4

### Trace-Based GC: Memory Life-Cycle



## Incremental GC

- **Interleaves GC with mutator action to reduce pause time**



$$\text{Ideal} = (R \cup \text{New}) - \text{Lost}$$

$$(R \cup \text{New}) - \text{Lost} \subseteq \text{Answer} \subseteq (R \cup \text{New})$$

## Effects of Mutation

- **Reachable set changes as mutator runs**
  - R: set of reachable objects before the mutator runs
  - Ideal: set of reachable objects at the end of the GC cycle
  - New: set of newly created objects
  - Lost: set of objects that become unreachable in the interim
  - $\text{Ideal} = (R \cup \text{New}) - \text{Lost}$
- **Ideal: Very expensive**
- **Conservative Incremental GC:**
  - May misclassify some unreachable as reachable**
    - should not include objects unreachable before GC starts
    - guarantees that garbage will be eliminated in the next round

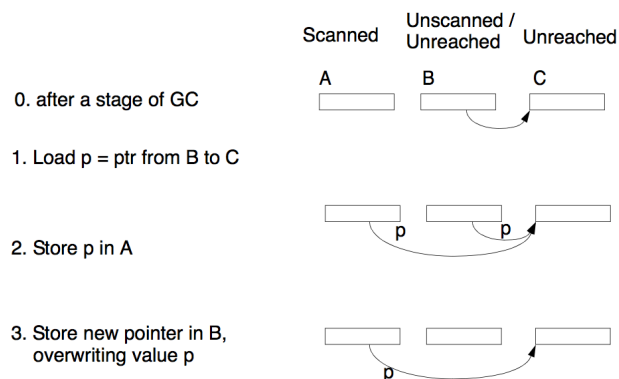
$$\text{Ideal} = (R \cup \text{New}) - \text{Lost} \subseteq \text{Answer} \subseteq (R \cup \text{New})$$

## Algorithm Proposal 1

- **Initial condition**
  - Scanned, Unscanned lists from before
- **To resume GC**
  - Find root sets
  - Place newly reached objects in “unscanned list”
  - Continue to trace reachability without redoing “scanned” objects
- **Did we find all reachable objects?**

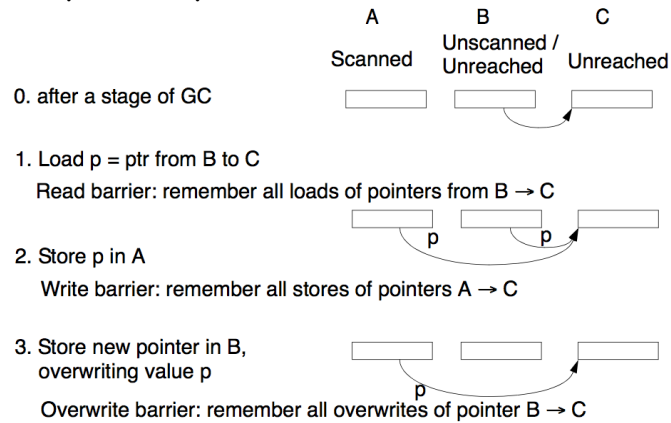
## Missed Reachable Objects

- **All reaching pointers are found in “scanned objects”**
- **Requires the occurrence of a 3-step sequence in the mutator:**



## Solution

- Intercept p in any of the three-step sequence
- Treat pointee of p as "unscanned"

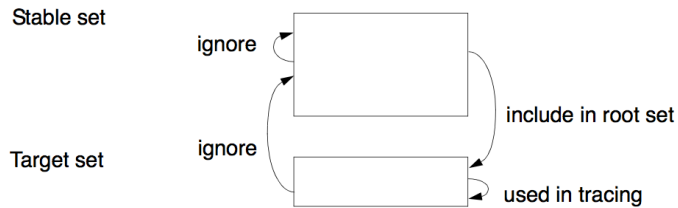


## Efficiency of Different Barriers

- **Most efficient: Write barrier**
  - less instances than read barrier
  - includes less unreachable objects than over-write barriers

## II. Partial GC

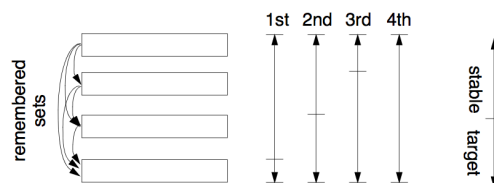
- Reduces pause time by collecting only objects in the target area:



- **Algorithm**
  - New "root set"
    - = original root set + pointers from Stable to Target set
  - Change program to intercept all writes to Stable set
- **Never misclassify reachable as unreachable**
- **May misclassify unreachable as reachable**

## Generational GC

- **Observation: objects die young**
  - 80-98% die within a few million instructions or before 1 MB has been allocated
- **Generational GC: collect newly allocated objects more often**



- **$i$ th generation**
  - new root set
    - = original root set + all pointers from generations  $j$  to  $i$  ( $j > i$ )
- **When 1st generation fills up**
  - GC copies reachable objects into 2nd generation, and so on.

## Properties

- **Never misclassify reachable as unreachable**
- **Misclassify unreachable as reachable**
  - when pointers in earlier generations are overwritten
  - eventually collect all garbage as generations get larger
- **Effective: time spent on objects that are mostly garbage**
- **GC of mature objects takes longer**
  - Size of target set increases
  - Eventually a full GC is performed

## Conclusions

- **Trace-based GC:**  
**find all reachable objects, complement to get unreachable**
  - 4 states: free, unreached, unscanned, scanned
  - break up reachability analysis
    - in time (incremental)
    - in space (partial: generational)